
Stabilized Finite Element Methods in Porous Media Flow

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LNCC/MCT

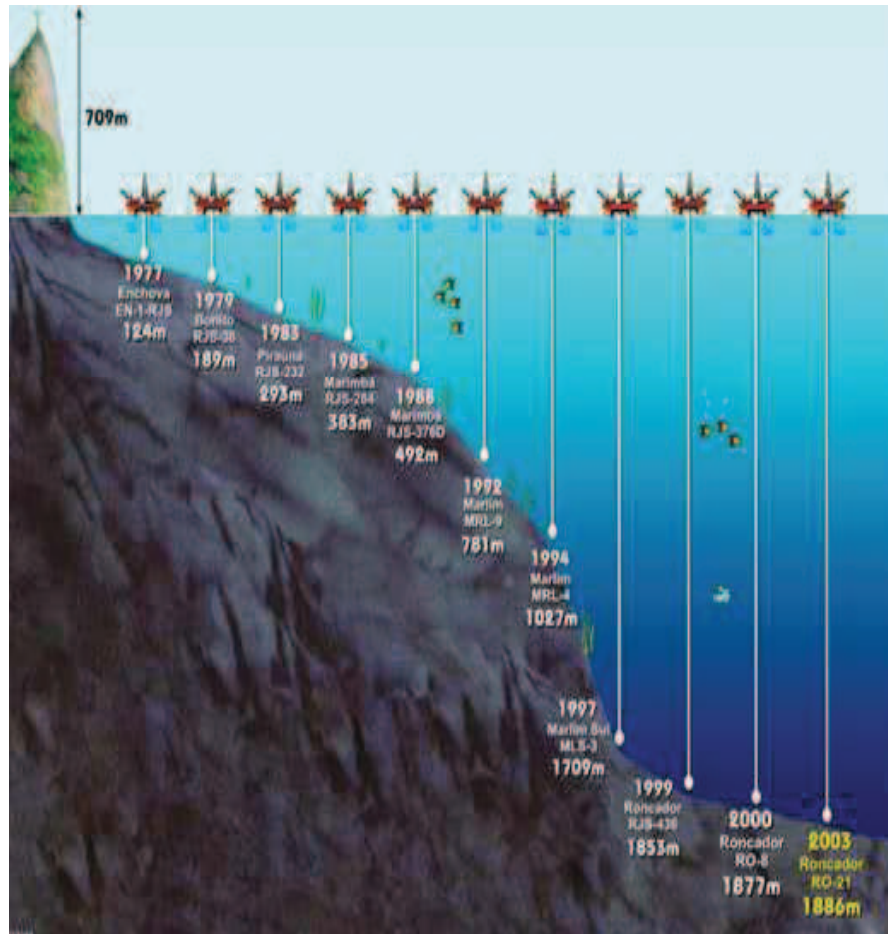
Laboratório Nacional de Computação Científica

Petrópolis, Rio de Janeiro

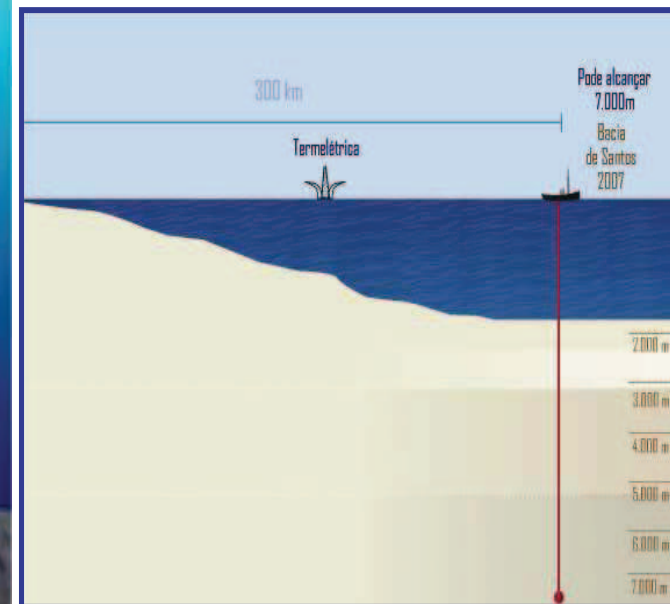
Brazil



Exemplos do impacto positivo da C,T&I no sucesso da economia do Brasil atual



2007- Tupi – 7000 m



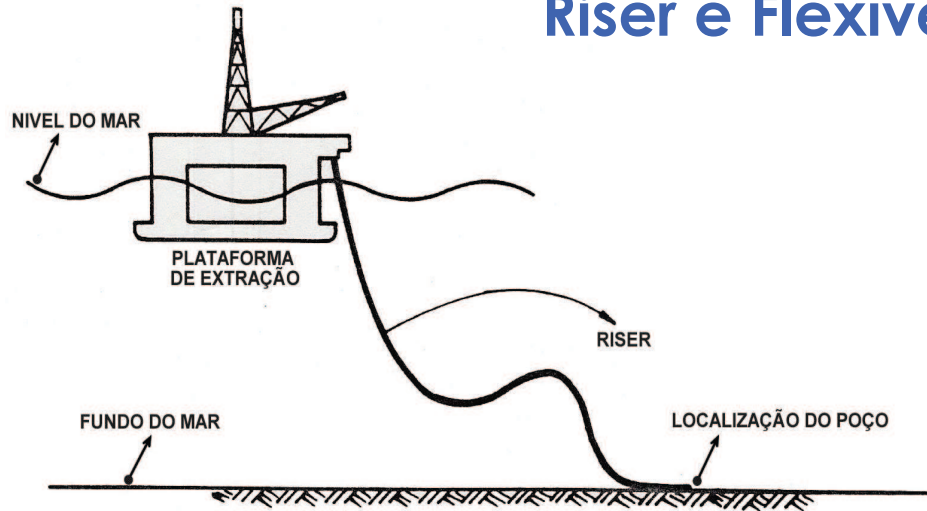
Líder em prospecção de óleo e gás em águas profundas

Record: 2.777 metros em 2007

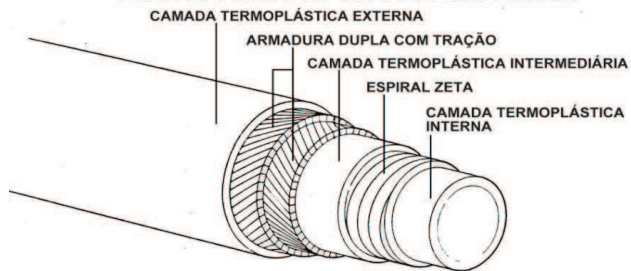
- 174m em 1977 no campo Enchovia EN-1 RJS
- 189m em 1979 no campo Bonito RJS-36
- 293m em 1983 no campo Piraúna RJS-232
- 383m em 1985 no campo Marimbá RJS-284
- 492m em 1988 no campo Marimbá RJS-3760
- 781m em 1992 no campo Marlim MRL-9
- 1.027m em 1994 no campo Marlim MRL-4
- 1.709m em 1997 no campo Marlim MLS-3
- 1.853m em 1999 no campo Roncador RJS-436
- 1.877m em 2000 no campo Roncador RO-8
- 1.886m em 2003 no campo Roncador RO-21

Risers and Flexibles

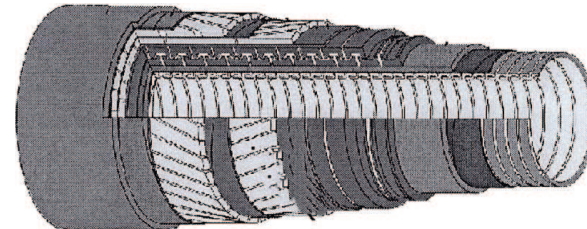
Riser e Flexíveis



ESTRUTURA TÍPICA DE UM RISER

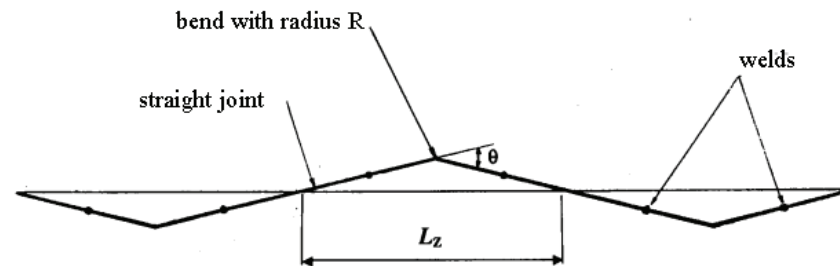
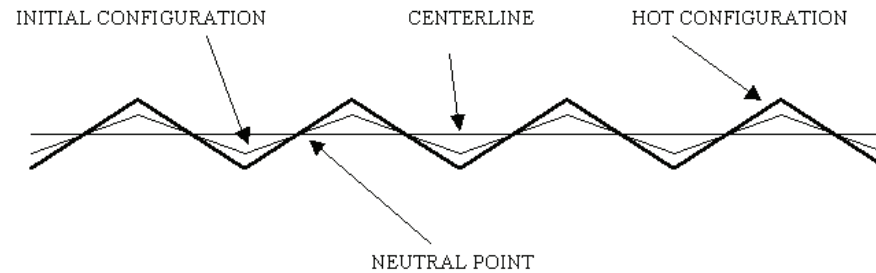


Secção de um riser



Zig-Zag Design Concept

Estudo da Sensibilidade do Duto em Zig-Zag

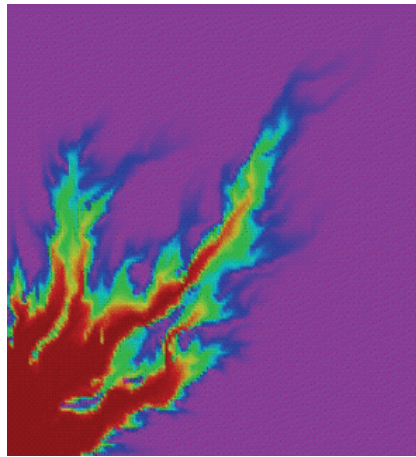


Porous Media Flow

Escoamento em Meios Porosos

Modelagem Matemática
Análise Numérica
Simulação Computacional

Aplicações a reservatórios de petróleo e águas subterrâneas,
tecidos biológicos e simulação de escoamento sanguíneos



Extração de Petróleo

Introduction

Miscible displacement in porous media:

$$\phi \frac{\partial c}{\partial t} + \mathbf{u} \cdot \nabla c - \operatorname{div}(D \nabla c) + \hat{f} c = g \quad \text{in } \Omega \times (0, T),$$

$$D = D(\mathbf{u}) = \alpha_m \mathbf{I} + |\mathbf{u}| \{ \alpha_l E(\mathbf{u}) + \alpha_t E^\perp(\mathbf{u}) \}$$

$$E(\mathbf{u}) = \frac{1}{|\mathbf{u}|^2} \mathbf{u} \otimes \mathbf{u}, \quad E^\perp(\mathbf{u}) = \mathbf{I} - E(\mathbf{u})$$

with the boundary and initial conditions

$$D \nabla c \cdot \mathbf{n} = 0 \quad \text{on } \partial \Omega \times (0, T)$$

$$c(\mathbf{x}, 0) = c_0(\mathbf{x}) \quad \text{on } \Omega$$

The velocity field \mathbf{u} is given by the Darcy flow model

Outline

- Introduction
- On finite element formulations for Darcy flow
 - Discontinuous Galerkin Methods
 - Dual mixed formulation
 - Hybridization
- Stabilized formulations
 - Stabilized dual mixed formulation
 - Stabilized dual hybrid mixed formulation
 - Hybridizable mixed DG method
- Approximations
- Numerical results
- Concluding remarks

Model problem - Darcy flow

Given the hydraulic conductivity tensor \mathbf{K} , with inverse $\mathbf{A} = \mathbf{K}^{-1}$, and a source term $f : \Omega \rightarrow \mathbb{R}$, find the hydraulic potential $p : \Omega \rightarrow \mathbb{R}$ and Darcy velocity $\mathbf{u} : \Omega \rightarrow \mathbb{R}^2$ such that:

$$\mathbf{A}\mathbf{u} = -\nabla p \quad \text{in } \Omega,$$

$$\operatorname{div} \mathbf{u} = f \quad \text{in } \Omega$$

$$\mathbf{u} \cdot \mathbf{n} = 0 \quad \text{on } \partial\Omega.$$

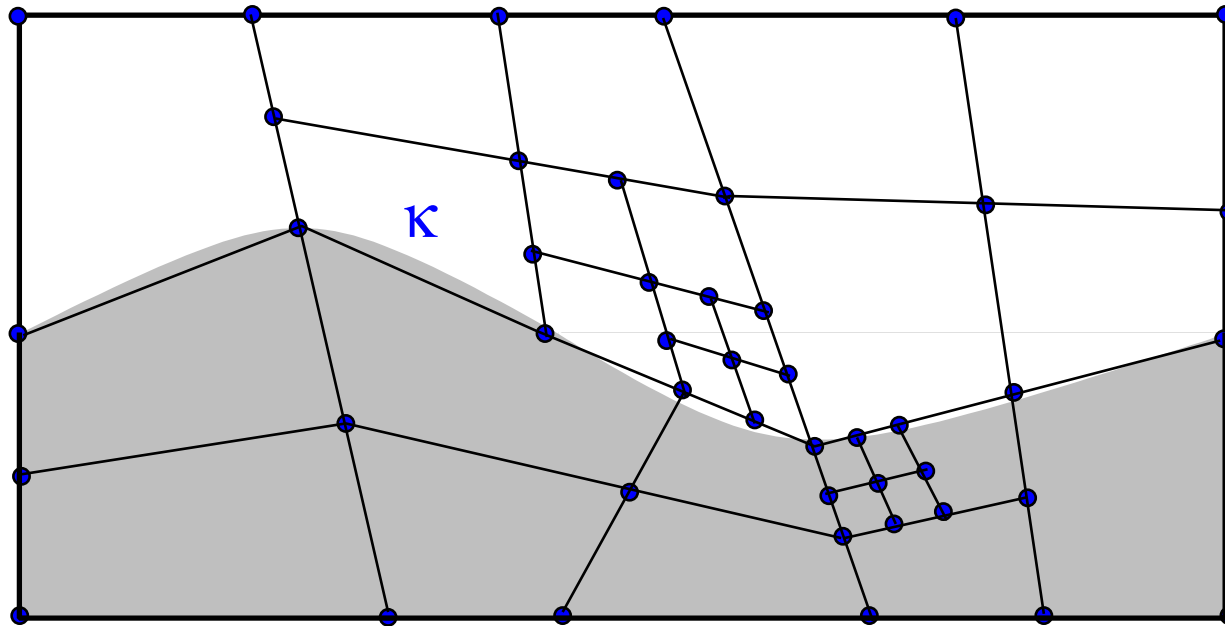
Equivalently

$$-\operatorname{div}(\mathbf{K}\nabla p) = f \quad \text{in } \Omega$$

$$\mathbf{K}\nabla p \cdot \mathbf{n} = 0 \quad \text{on } \partial\Omega.$$

Why discontinuous formulations?

- Adaptivity (unstructured and irregular meshes)
- Domain decomposition
- Conservation
- Stabilization



On Discontinuous FE formulations

Edges, averages and jumps

Regular partition of Ω : $\mathcal{T}_h = \{\mathcal{K}\} :=$ union of all elements \mathcal{K}

All edges : $\mathcal{E}_h = \{e : e \text{ is an edge of } \mathcal{K} \text{ for all } \mathcal{K} \in \mathcal{T}_h\}$

Interior edges : $\mathcal{E}_h^0 = \{e \in \mathcal{E}_h \mid e \text{ is an interior edge}\}$

Boundary edges : $\mathcal{E}_h^\partial = \mathcal{E}_h \cap \partial\Omega,$

Averages and jumps:

Scalar function : $\{\varphi\} = \frac{1}{2}(\varphi^1 + \varphi^2), \quad [[\varphi]] = \varphi^1 \mathbf{n}^1 + \varphi^2 \mathbf{n}^2 \quad \text{on } e \in \mathcal{E}^0$

Vector function : $\{\mathbf{v}\} = \frac{1}{2}(\mathbf{v}^1 + \mathbf{v}^2), \quad [[\mathbf{v}]] = \mathbf{v}^1 \cdot \mathbf{n}^1 + \mathbf{v}^2 \cdot \mathbf{n}^2 \quad \text{on } e \in \mathcal{E}^0.$

Darcy flow in heterogeneous media

Broken space formulation

Find the hydraulic potential $p : \Omega \rightarrow \mathbb{R}$ such that:

$$-\operatorname{div} (K \nabla p) = f \quad \text{in each } \mathcal{K} \in \mathcal{T}_h$$

with interface conditions:

$$[[p]]|_e = 0 \quad \text{on each edge } e \in \mathcal{E}_h^0.$$

$$[[K \nabla p]]|_e = 0 \quad \text{on each edge } e \in \mathcal{E}_h^0.$$

and boundary condition:

$$K \nabla p \cdot \mathbf{n} = 0 \quad \text{on each edge } e \in \mathcal{E}_h^\partial = \mathcal{E}_h \cap \partial\Omega.$$

DGFEM - IP formulation

Find $p \in \mathcal{U}$ such that

$$b(p, q) = l(q) := \sum_{\kappa \in \mathcal{T}_h} \int_{\kappa} f q d\Omega \quad \forall q \in \mathcal{U}$$

$$\mathcal{U} = \{q \in L^2(\Omega) : q|_{\kappa} \in H^2(\kappa) \quad \forall \kappa \in \mathcal{T}_h\},$$

$$b(p, q) = \sum_{\kappa \in \mathcal{T}_h} \int_{\kappa} \mathbf{K} \nabla p \cdot \nabla q d\Omega + b_{\partial}(p, q),$$

$$b_{\partial}(p, q) = \int_{\mathcal{E}_h^0} (\lambda [[p]] \{\mathbf{K} \nabla q \cdot \mathbf{n}\} - \{\mathbf{K} \nabla p \cdot \mathbf{n}\} [[q]] + \beta [[p]] [[q]]) ds$$

- $\lambda = -1$ for SIP formulation: Douglas Arnold 1982
- $\lambda = 1$ for NSIP formulation, $\lambda = 0$ for Neutral formulation

Abstract Mixed Formulation

$$A\mathbf{u} + B^*p = g \quad \text{in } \Omega$$

$$B\mathbf{u} = f \quad \text{in } \Omega$$

Weak form: Find $\{\mathbf{u}, p\} \in W \times V$ such that

$$a(\mathbf{u}, \mathbf{v}) + b(\mathbf{v}, p) - g(\mathbf{v}) + b(\mathbf{u}, q) - f(q) = 0 \quad \forall \{\mathbf{v}, q\} \in W \times V$$

Babuška - Brezzi / Inf-sup conditions:

$$\sup_{\mathbf{v} \in W} \frac{a(\mathbf{u}, \mathbf{v})}{\|\mathbf{v}\|_W} \geq \alpha \|\mathbf{u}\|_W \quad \forall \mathbf{u} \in K_0$$

$$\sup_{\mathbf{v} \in W} \frac{b(\mathbf{v}, q)}{\|\mathbf{v}\|_W} \geq \beta \|q\|_V \quad \forall q \in V$$

$$K_0 = \{\mathbf{v} \in W, b(\mathbf{v}, q) = 0 \quad \forall q \in V\}$$

References o mixed methods

- I. Babuška and A.K. Aziz (1972). *Lectures on the mathematical foundation of the finite element method*. University of Maryland, Technical Note BN-748
- I. Babuška (1973). *The finite element method with Lagrange multipliers*. Numer. Math. 20:179-192
- F. Brezzi (1974). *On the existence, uniqueness and approximation of saddle-point problems arising from Lagrange multipliers*. R.A.I.R.O Anal. Numer. R2:129-151
- J.T. Oden and J.N. Reddy (1976). *An introduction to the mathematical theory of the finite elements*. John Wiley & Sons
- P.A. Raviart and J.M. Thomas (1977). *A mixed finite element method for second order elliptic problems*. Lecture Notes in Mathematics 606. Springer-Verlag

GLS Stabilization

- Mixed Petrov-Galerkin method (Galerkin least-squares): Find $\{\mathbf{u}, p\} \in W \times V$ such that $\forall \{\mathbf{v}, q\} \in W \times V$

$$a(\mathbf{u}, \mathbf{v}) + b(\mathbf{v}, p) - g(\mathbf{v}) + b(\mathbf{u}, q) - f(q) +$$

$$\delta_1(A\mathbf{u} + B^*p - g, A\mathbf{v} + B^*q)_h + \delta_2(B\mathbf{u} - f, Bv)_h = 0$$

- Loula, Hughes, Franca and Miranda (1987). *Mixed Petrov-Galerkin method for the Timoshenko beam*. CMAME, 63:133-154
- Franca, Hughes, Loula and Miranda (1988). *A New family of stable elements for nearly incompressible elasticity based on a mixed Petrov-Galerkin method*. Numer. Math. 53:123-141

Dual mixed formulation for Darcy flow

Find $[\mathbf{u}, p] \in W \times V$ such that

$$(\mathbf{A}\mathbf{u}, \mathbf{v}) - (p, \operatorname{div}\mathbf{v}) = 0 \quad \forall \mathbf{v} \in W$$

$$-(\operatorname{div}\mathbf{u}, q) - (f, q) = 0 \quad \forall q \in V$$

For $V = L^2(\Omega)/\mathbb{R}$ and $W = \{\mathbf{v} \in H(\operatorname{div}) : \mathbf{v} \cdot \mathbf{n} = 0 \text{ on } \partial\Omega\}$

with associated norms:

$$\|p\|^2 = (p, p) \quad \forall p \in V,$$

$$\|\mathbf{u}\|_W^2 = \|\mathbf{u}\|_{H(\operatorname{div})}^2 = (\mathbf{u}, \mathbf{u}) + (\operatorname{div}\mathbf{u}, \operatorname{div}\mathbf{u}) \quad \forall \mathbf{u} \in W$$

- Stability is proved since $\operatorname{div}(W) = V$
- Raviart & Thomas, 1977

Stabilization in $[H^1(\Omega)]^2 \times H^1(\Omega)$

C^0 Lagrangian formulation

$$\mathcal{U} = \{\mathbf{v} \in [H^1(\Omega)]^2, \mathbf{v} \cdot \mathbf{n} = 0 \text{ on } \partial\Omega\}; \quad \mathcal{Q} = H^1(\Omega)/\mathbb{R}.$$

CGLS : Find $\{\mathbf{u}, p\} \in \mathcal{U} \times \mathcal{Q}$ such that

$$\begin{aligned} & (\mathbf{A}\mathbf{u}, \mathbf{v}) - (\operatorname{div}\mathbf{v}, p) - (\operatorname{div}\mathbf{u}, q) + (f, q) \quad (\text{Galerkin}) \\ & - \frac{1}{2} (\mathbf{K}(\mathbf{A}\mathbf{u} + \nabla p), \mathbf{A}\mathbf{v} + \nabla q) + (|\mathbf{A}|(\operatorname{div}\mathbf{u} - f), \operatorname{div}\mathbf{v}) \quad (\text{GLS}) \\ & + (|\mathbf{K}|\operatorname{rot}(\mathbf{A}\mathbf{u}), \operatorname{rot}(\mathbf{A}\mathbf{v})) = 0 \quad \forall [\mathbf{v}, q] \in \bar{\mathcal{U}} \times \mathcal{Q} \end{aligned}$$

- Unconditional stability is proved
- M.R. Correa and A.F. Loula, *Unconditionally stable mixed finite element methods for Darcy flow*, CMAME, 197 (2008).

Stability. Babuška's lema

Given the stabilized bilinear form,

$$\begin{aligned} A([\mathbf{u}, p], [\mathbf{v}, q]) &= (\mathbf{A}\mathbf{u}, \mathbf{v}) - (\operatorname{div}\mathbf{v}, p) - (\operatorname{div}\mathbf{u}, q) \\ &\quad - \frac{1}{2} (\mathbf{K}(\lambda\mathbf{u} + \nabla p), \mathbf{A}\mathbf{v} + \nabla q) \\ &\quad + (|\mathbf{A}|(\operatorname{div}\mathbf{u}, \operatorname{div}\mathbf{v}) + (|\mathbf{K}|\operatorname{rot}(\mathbf{A}\mathbf{u}), \operatorname{rot}(\mathbf{A}\mathbf{v}))) \end{aligned}$$

for any pair $[\mathbf{u}, p]$, we can always find $\bar{\mathbf{v}} = \mathbf{u}$ and $\bar{q} = -p$ such that

$$\sup_{[\mathbf{v}, q] \in \bar{\mathcal{U}} \times \mathcal{Q}} \frac{|A([\mathbf{u}, p], [\mathbf{v}, q])|}{\|[\mathbf{v}, q]\|_{\bar{\mathcal{U}} \times \mathcal{Q}}} \geq \frac{|A([\mathbf{u}, p], \{\bar{\mathbf{v}}, \bar{q}\})|}{\|\{\bar{\mathbf{v}}, \bar{q}\}\|_{\bar{\mathcal{U}} \times \mathcal{Q}}} \geq \alpha \|[\mathbf{u}, p]\|_{\bar{\mathcal{U}} \times \mathcal{Q}}$$

with $\alpha > 0$ and

$$\|[\mathbf{u}, p]\|_{\bar{\mathcal{U}} \times \mathcal{Q}} = (\|\mathbf{u}\|^2 + \|\nabla\mathbf{u}\|^2 + \|\nabla p\|^2)^{1/2}$$

Numerical analysis

- Conforming approximations are $[H^1(\Omega)]^2 \times H^1(\Omega)$ stable
- Any C^0 Lagrangian interpolation is stable

Error estimates:

(Optimal for equal order C^0 Lagrangian approximations $l = k$):

$$\|p - p_h\| + h\|\nabla p - \nabla p_h\| \leq Ch^{k+1} (|\mathbf{u}|_{k+1} + |p|_{k+1}),$$

$$\|\mathbf{u} - \mathbf{u}_h\|_1 \leq Ch^k (|\mathbf{u}|_{k+1} + |p|_{k+1}),$$

$$\|\operatorname{div} \mathbf{u} - \operatorname{div} \mathbf{u}_h\| \leq Ch^k (|\mathbf{u}|_{k+1} + |p|_{k+1}).$$

- Optimal for pressure in $L^2(\Omega)$ and $H^1(\Omega)$ norms
 - Optimal for velocity in $[L^2(\Omega)]^2$ and $[H^1(\Omega)]^2$ norms
-

Darcy flow in heterogeneous media

Mixed formulation in Broken space formulation.

Find the hydraulic potential $p : \Omega \rightarrow \mathbb{R}$ and Darcy velocity $\mathbf{u} : \Omega \rightarrow \mathbb{R}^2$ such that:

$$\operatorname{div} \mathbf{u} = f \quad \text{in each } \mathcal{K} \in \mathcal{T}_h$$

$$\mathbf{u} = -K \nabla p \quad \text{in each } \mathcal{K} \in \mathcal{T}_h$$

with interface and boundary conditions

$$[[p]]|_e := p^1 \mathbf{n}^1 + p^2 \mathbf{n}^2 = 0 \quad \text{on each edge } e \in \mathcal{E}_h^0.$$

$$[[\mathbf{u}]]|_e := \mathbf{u}^1 \cdot \mathbf{n}^1 + \mathbf{u}^2 \cdot \mathbf{n}^2 = 0 \quad \text{on each edge } e \in \mathcal{E}_h.$$

$$\mathbf{u} \cdot \mathbf{n} = 0 \quad \text{on each edge } e \in \mathcal{E}_h^\partial = \mathcal{E}_h \cap \partial\Omega.$$

Hybrid methods: Pian & Tong

Some references:

- P. Tong and T.H.H. Pian, *A variational principle and the convergence of a finite-element method based on assumed stress distribution*, 1969, Int. J. Solids Struct. Vol 5, 463-472.
- E.C.P. Lima, *Finite elements for plate bending with assumed stress fields*, 1972, MSc Thesis, COPPE/UFRJ .
- P.A. Raviart and J.M. Thomas *Primal hybrid finite element methods for 2nd order elliptic equations*, 1977, Mathematics of Computation 31, 391-413.
- D.N. Arnold and F. Brezzi, *Mixed and Nonconforming finite element methods: implementation, post-processing and error estimates*, 1985, RAIRO MMAN. Vol 19, 7-32.

Hybridization

On a regular finite element mesh \mathcal{T}_h , on each element \mathcal{K} we define

$$Q_{\mathcal{K}} = \{q \in L^2(\mathcal{K}) \forall \mathcal{K} \in \mathcal{T}_h\},$$

$$U_{\mathcal{K}} = \{\mathbf{v} \in L^2(\mathcal{K}) \times L^2(\mathcal{K}), \operatorname{div} \mathbf{v} \in L^2(\mathcal{K}) \forall \mathcal{K} \in \mathcal{T}_h\},$$

And consider a local weak form of the equation $\mathbf{A}\mathbf{u} + \nabla p = 0$:

$$(\mathbf{A}\mathbf{u} + \nabla p, \mathbf{v})_{\mathcal{K}} = \int_{\mathcal{K}} \mathbf{A}\mathbf{u} \cdot \mathbf{v} d\Omega - \int_{\mathcal{K}} p \operatorname{div} \mathbf{v} d\Omega + \int_{\partial \mathcal{K}} p \mathbf{v} \cdot \mathbf{n} ds = 0$$

in each element \mathcal{K}

Local problems

Given $p = \bar{p}$ on $\partial\mathcal{K}$, we can solve the local problem:

LP: For each $\mathcal{K} \in \mathcal{T}_h$, find $[\mathbf{u}, p] \in U_{\mathcal{K}} \times Q_{\mathcal{K}}$, such that

$$a_{\mathcal{K}}([\mathbf{u}, p], [\mathbf{v}, q]) = f_{\mathcal{K}}([\mathbf{v}, q]) \quad \forall [\mathbf{v}, q] \in U_{\mathcal{K}} \times Q_{\mathcal{K}}.$$

with

$$a_{\mathcal{K}}([\mathbf{u}, p], [\mathbf{v}, q]) = (\mathbf{A}\mathbf{u}, \mathbf{v})_{\mathcal{K}} - (p, \operatorname{div}\mathbf{v})_{\mathcal{K}} - (\operatorname{div}\mathbf{u}, q)_{\mathcal{K}},$$

$$f_{\mathcal{K}}([\mathbf{v}, q]) = -(f, q)_{\mathcal{K}} - c_{\mathcal{K}}(\bar{p}, \mathbf{v}),$$

$$c_{\mathcal{K}}(\bar{p}, \mathbf{v}) = \int_{\partial\mathcal{K}} \bar{p} \mathbf{v} \cdot \mathbf{n} ds,$$

FEM: Local Raviart-Thomas or BDM finite element on each \mathcal{K} .

Dual hybrid mixed formulation

Arnold & Brezzi (1985): Find $[\mathbf{u}, p] \in U \times Q$ and $\lambda \in M$, such that

$$a([\mathbf{u}, p], [\mathbf{v}, q]) + c(\lambda, \mathbf{v}) = f([\mathbf{v}, q]), \quad \forall [\mathbf{v}, q] \in U \times Q,$$

$$c(\mu, \mathbf{u}) = 0 \quad \forall \mu \in M,$$

with $M = \{\mu \in L^2(e) \mid \forall e \in \mathcal{E}_h^0\}$, $U = \prod_{\mathcal{K}} U_{\mathcal{K}}$, $Q = \prod_{\mathcal{K}} Q_{\mathcal{K}}$,

$$a([\mathbf{u}, p], [\mathbf{v}, q]) = \sum_{\mathcal{K}} a_{\mathcal{K}}([\mathbf{u}, p], [\mathbf{v}, q]) \quad \forall [\mathbf{u}, p], [\mathbf{v}, q] \in U \times Q$$

$$c(\mu, \mathbf{v}) = \sum_{\mathcal{K}} c_{\mathcal{K}}(\mu, \mathbf{v}) = \int_{\mathcal{E}^0} \mu [[\mathbf{v}]] ds \quad \forall \mu \in M, \quad \forall \mathbf{v} \in U$$

$$f([\mathbf{v}, q]) = \sum_{\mathcal{K}} (f, q) - \int_{\mathcal{E}_h^{\partial}} g \mathbf{v} \cdot \mathbf{n} ds \quad \forall \mathbf{v} \in U, \quad \forall q \in Q$$

Stabilized DHM formulation

SDHM: Find $[\mathbf{u}, p] \in U \times Q$ and $\lambda \in M$ such that

$$a_\delta([\mathbf{u}, p], [\mathbf{v}, q]) + c(\lambda, \mathbf{v}) + \sum_{\mathcal{K}} \int_{\partial\mathcal{K}} \beta(p - \lambda) q ds = f_\delta([\mathbf{v}, q]) \quad \forall [\mathbf{v}, q] \in U \times Q$$

$$c(\mu, \mathbf{u}) + \sum_{\mathcal{K}} \int_{\partial\mathcal{K}} \beta(\lambda - p) \mu ds = 0 \quad \forall \mu \in M$$

$$\begin{aligned} a_\delta([\mathbf{u}_h, p_h], [\mathbf{v}_h, q_h]) &= a([\mathbf{u}_h, p_h], [\mathbf{v}_h, q_h]) \\ &+ \delta_1 \sum_{\mathcal{K}} (|\mathbf{A}| \operatorname{div} \mathbf{u}, \operatorname{div} \mathbf{v})_{\mathcal{K}} + \delta_2 \sum_{\mathcal{K}} (\mathbf{K} (\mathbf{A} \mathbf{u} + \nabla p), \mathbf{A} \mathbf{v} + \nabla q)_{\mathcal{K}} \\ &+ \delta_3 \sum_{\mathcal{K}} (|\mathbf{K}| \operatorname{rot}(\mathbf{A} \mathbf{u}), \operatorname{rot}(\mathbf{A} \mathbf{v}))_{\mathcal{K}} \end{aligned}$$

$$f_\delta([\mathbf{v}, q]) = f([\mathbf{v}, q]) + \sum_{\mathcal{K}} \delta_1 (|\mathbf{A}| f, \operatorname{div} \mathbf{v})_{\mathcal{K}}$$

Hybridizable mixed DG method

Solving first the multiplier equation we get

$$\lambda = \{p\} - \frac{1}{2\beta} \llbracket \mathbf{u} \rrbracket.$$

yielding the stabilized mixed discontinuous Galerkin formulation

SMDG: Find $[\mathbf{u}, p]$ such that

$$\begin{aligned} a_\delta([\mathbf{u}, p], [\mathbf{v}, q]) + \int_{\mathcal{E}_h^0} (\{p\} \llbracket \mathbf{v} \rrbracket + \llbracket \mathbf{u} \rrbracket \{q\}) ds \\ + \int_{\mathcal{E}_h^0} \frac{\beta}{2} \llbracket p \rrbracket \cdot \llbracket q \rrbracket ds - \int_{\mathcal{E}_h^0} \frac{1}{2\beta} \llbracket \mathbf{u} \rrbracket \llbracket \mathbf{v} \rrbracket ds = f_\delta([\mathbf{v}, q]) \quad \forall [\mathbf{v}, q] \in U \times Q \end{aligned}$$

Setting $\delta_i = 0$, for $i = 1, 2, 3$, **SMDG** recovers the LDG-H (Local Discontinuous Galerkin - Hybridizable formulation).

B. Cockburn and Coworkers, Math. Comp. 2010.

Finite element approximations

SDHM_h: Find $[\mathbf{u}_h, p_h] \in U_h^m \times Q_h^l$ and $\lambda_h \in M_h^n$ such that

$$a_\delta([\mathbf{u}_h, p_h], [\mathbf{v}_h, q_h]) + \int_{\mathcal{E}_h^0} \frac{\beta}{2} \llbracket p_h \rrbracket \cdot \llbracket q_h \rrbracket ds + \int_{\mathcal{E}_h^0} \lambda_h \llbracket \mathbf{v}_h \rrbracket ds \\ + \int_{\mathcal{E}_h^0} 2\beta (\{p_h\} - \lambda_h) \{q_h\} ds = f_\delta([\mathbf{v}_h, q_h]) \quad \forall [\mathbf{v}_h, q_h] \in U_h^m \times Q_h^l$$

$$\int_{\mathcal{E}_h^0} 2\beta ((\lambda_h - \{p_h\}) + \llbracket \mathbf{u}_h \rrbracket) \mu_h ds = 0 \quad \forall \mu_h \in M_h.$$

$$Q_h^l = \{q \in Q : q|_{\mathcal{K}} \in \mathcal{P}^l(\mathcal{K}) \quad \forall \mathcal{K} \in \mathcal{T}_h\},$$

$$U_h^m = \{\mathbf{v} \in U : \mathbf{v}|_{\mathcal{K}} \in \mathcal{P}^m(\mathcal{K}) \times \mathcal{P}^m(\mathcal{K}) \quad \forall \mathcal{K} \in \mathcal{T}_h\},$$

$$M_h^n = \{\mu \in M : \mu|_e \in \mathcal{P}^n(e) \quad \forall e \in \mathcal{E}^0\}$$

Hybridizable DG FEM

For $n \geq l$ and $n \geq m$ we can solve explicitly the finite element equation for the multiplier λ_h , obtaining

$$\lambda_h = \{p_h\} - \frac{1}{2\beta} \llbracket \mathbf{u}_h \rrbracket,$$

and yielding the following HDG method

SMDG_h : Find $[\mathbf{u}_h, p_h] \in U_h^m \times Q_h^l$ such that $\forall [\mathbf{v}_h, q_h] \in U_h \times Q_h$

$$a_\delta([\mathbf{u}_h, p_h], [\mathbf{v}_h, q_h]) + \int_{\mathcal{E}_h^0} (\{p_h\} \llbracket \mathbf{v}_h \rrbracket + \llbracket \mathbf{u}_h \rrbracket \{q_h\}) ds + \int_{\mathcal{E}_h^0} \frac{\beta}{2} \llbracket p_h \rrbracket \cdot \llbracket q_h \rrbracket ds - \int_{\mathcal{E}_h^0} \frac{1}{2\beta} \llbracket \mathbf{u}_h \rrbracket \llbracket \mathbf{v}_h \rrbracket ds = f_\delta([\mathbf{v}_h, q_h])$$

Convergence studies

Darcy flow in homogeneous media:

Given $\mathbf{K} = \mathbf{I}$, $[\mathbf{u}, p]$ in $\Omega = [-1, 1] \times [-1, 1]$ and

$f(x, y) = \cos(\pi x) \cos(\pi y)$ such that:

$$p = \frac{1}{2\pi^2} \cos \pi x \cos \pi y; \quad \mathbf{u} = \frac{1}{2\pi} \begin{bmatrix} \sin \pi x \cos \pi y \\ \cos \pi x \sin \pi y \end{bmatrix}$$

Equal order polynomial spaces for all fields: $l = n = m$

DHM (No stabilization) : $\delta_1 = \delta_2 = \delta_3 = \beta = 0$ (Unstable)

LDG – H(Penalty) : $\delta_1 = \delta_2 = \delta_3 = 0; \beta = 1$ (Not optimal)

SDHM : $\delta_1 = 0.5; \delta_2 = -0.5; \delta_3 = 0.5; \beta = 0$

Convergence study

Homogeneous medium

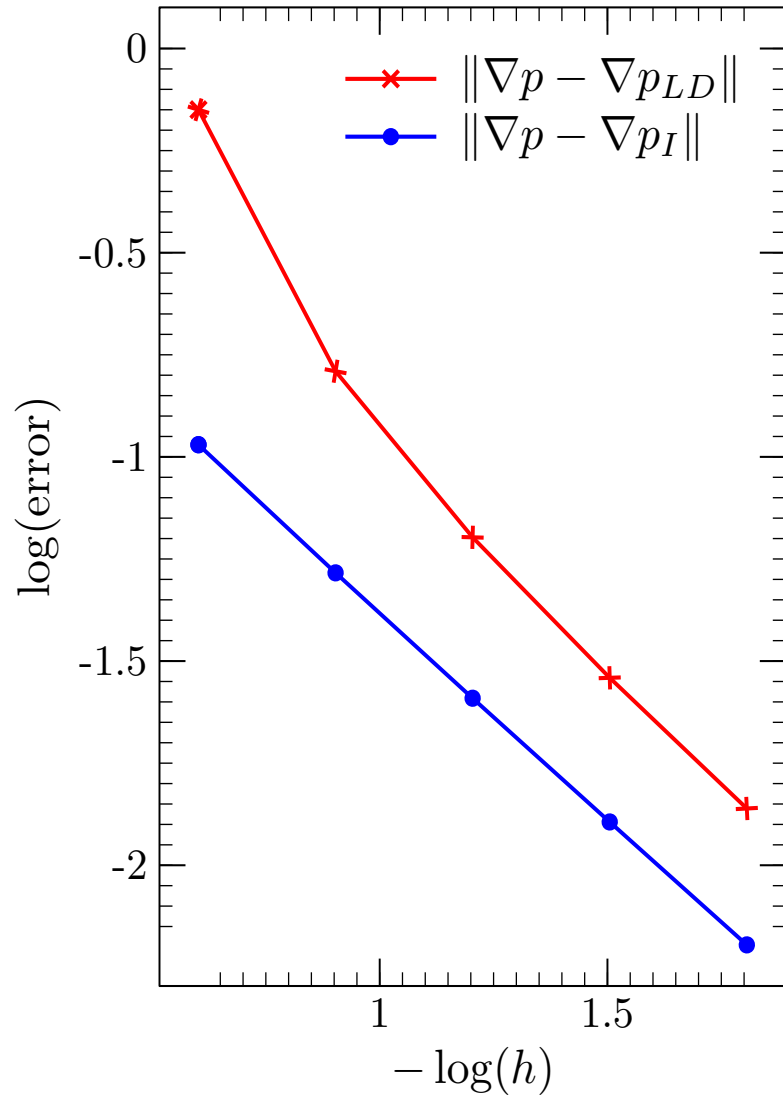
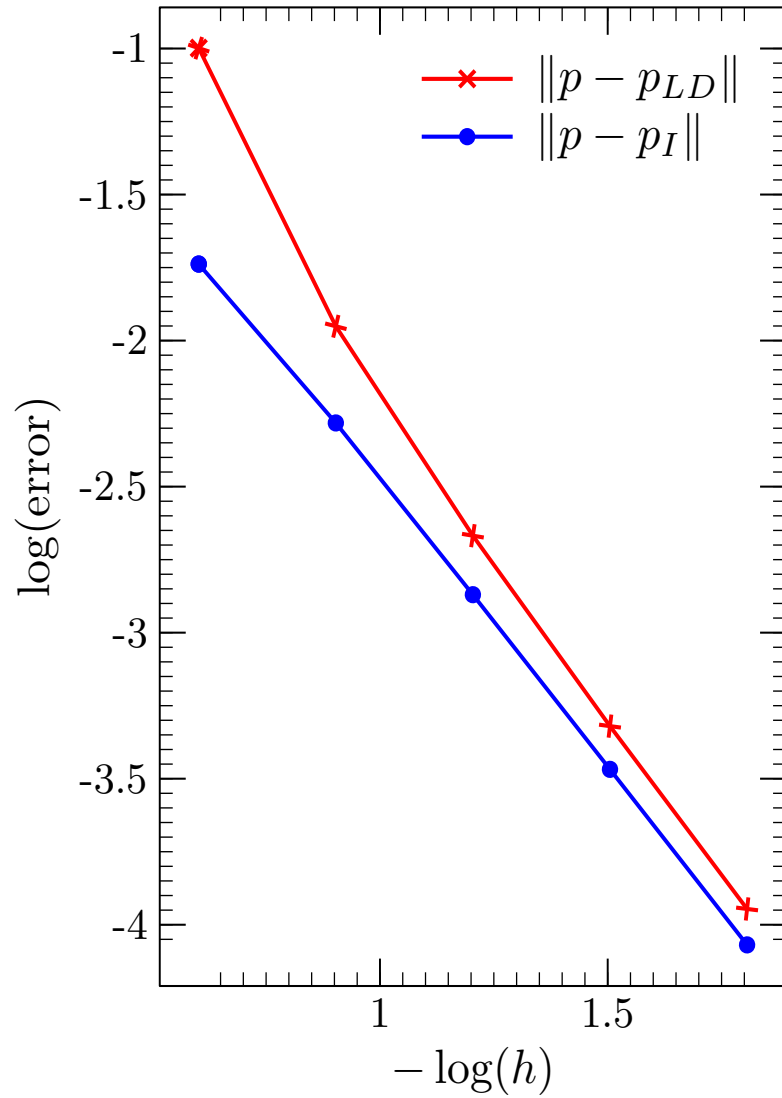
Given $\mathbf{K} = \mathbf{I}$, $[\mathbf{u}, p]$ in $\Omega = [-1, 1] \times [-1, 1]$ such that:

$$\begin{aligned} \operatorname{div} \mathbf{u} &= \cos(\pi x) \cos(\pi y) && \text{in } \Omega \\ \mathbf{u} &= -\nabla p && \text{in } \Omega \\ \mathbf{u} \cdot \mathbf{n} &= 0 && \text{on } \partial\Omega \end{aligned}$$

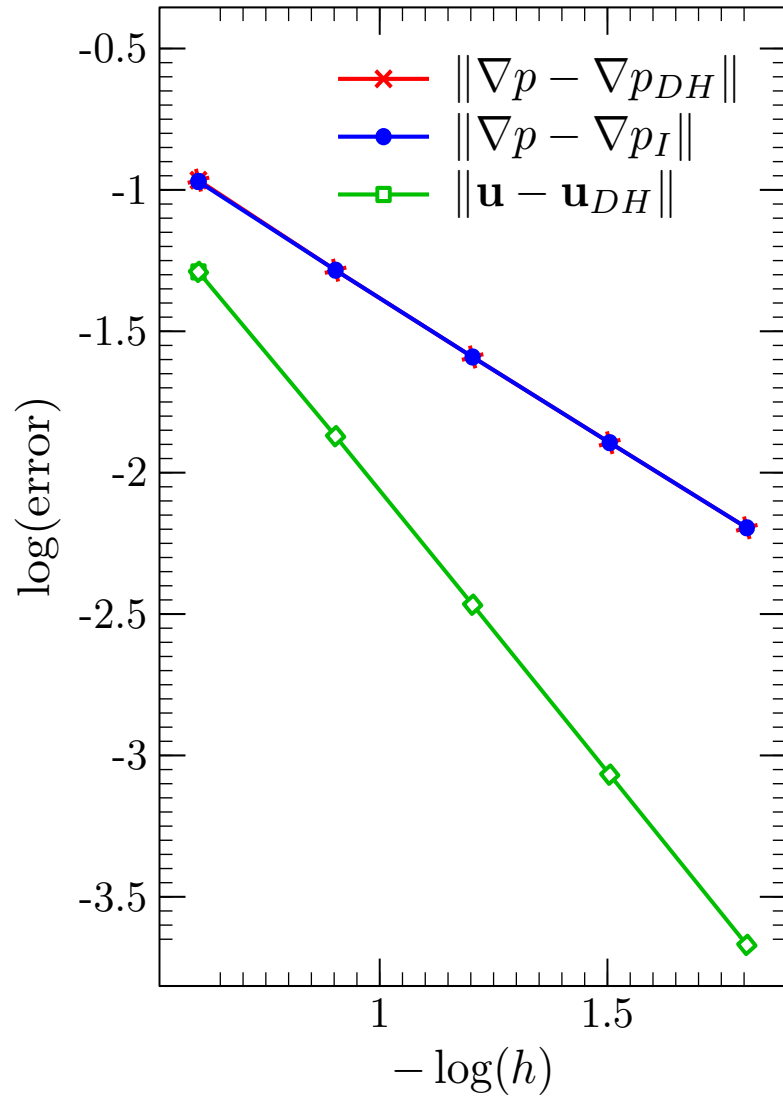
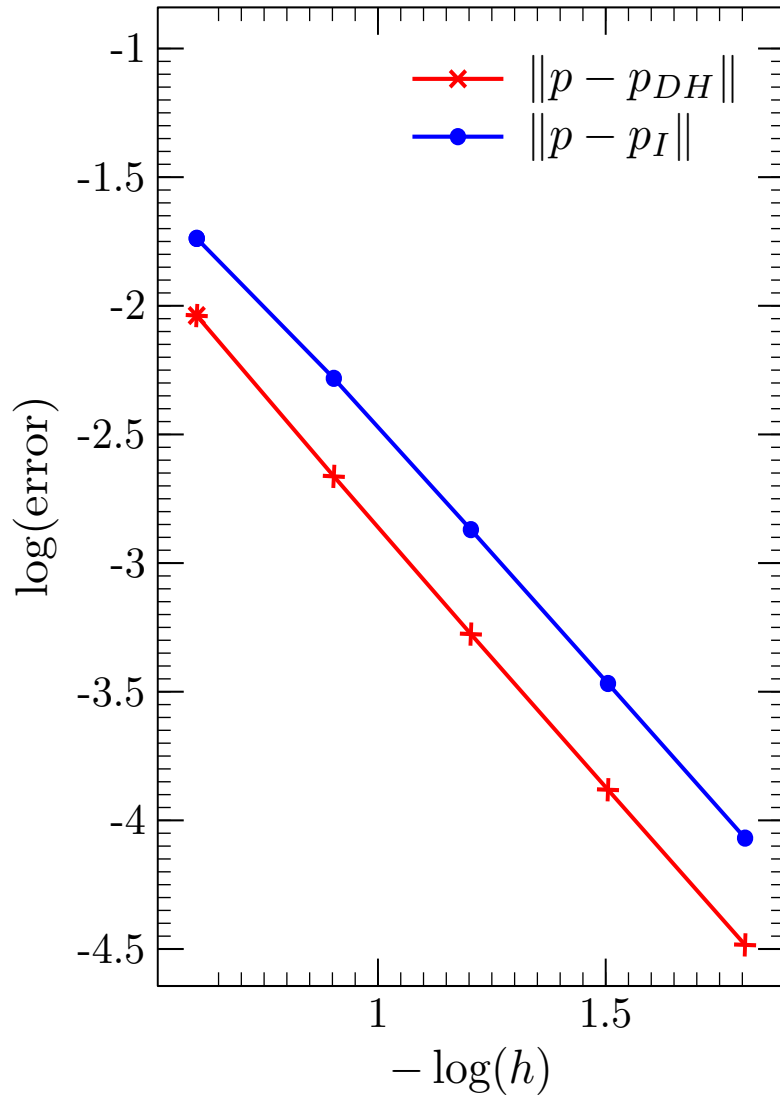
Exact solution:

$$\begin{aligned} p &= \frac{1}{2\pi^2} \cos \pi x \cos \pi y \\ \mathbf{u} &= \frac{1}{2\pi} \begin{bmatrix} \sin \pi x \cos \pi y \\ \cos \pi x \sin \pi y \end{bmatrix} \end{aligned}$$

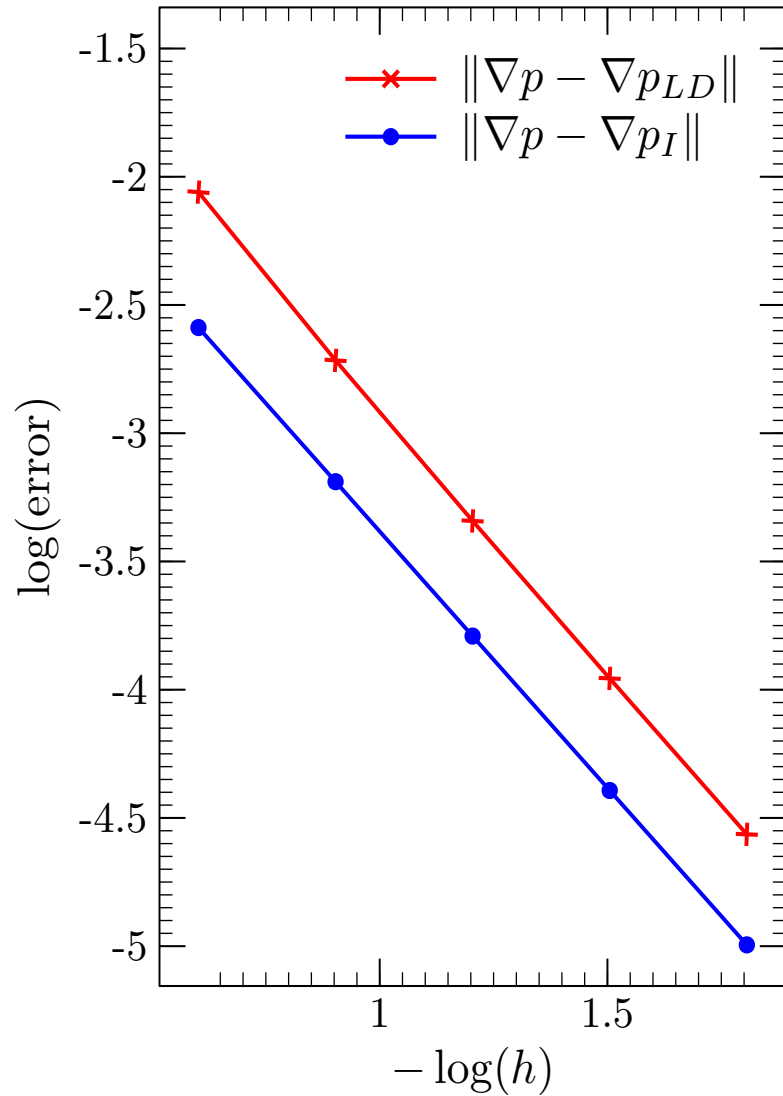
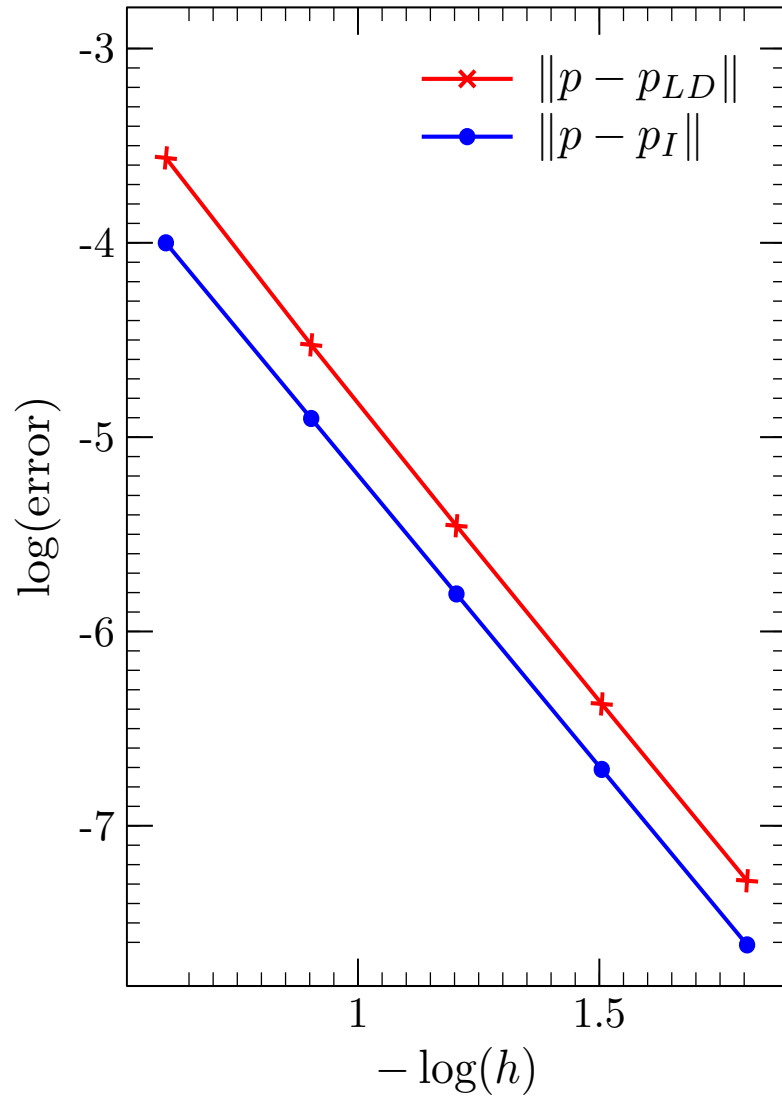
LDG-H ($l = 1$)



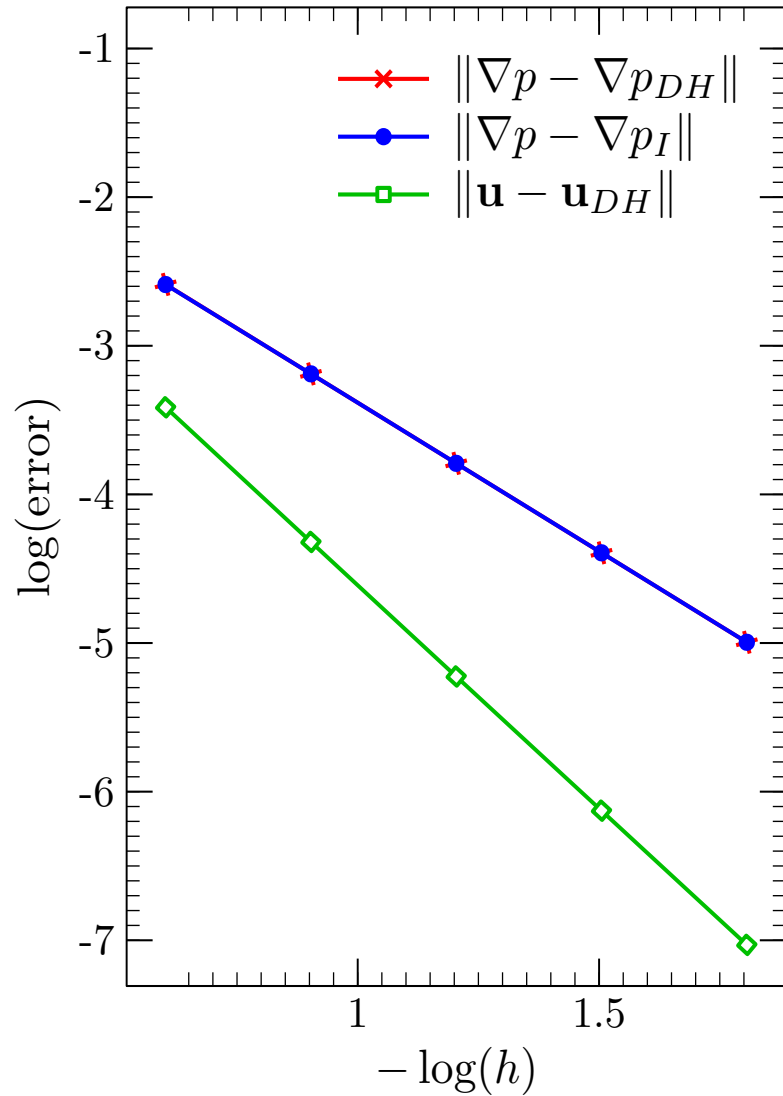
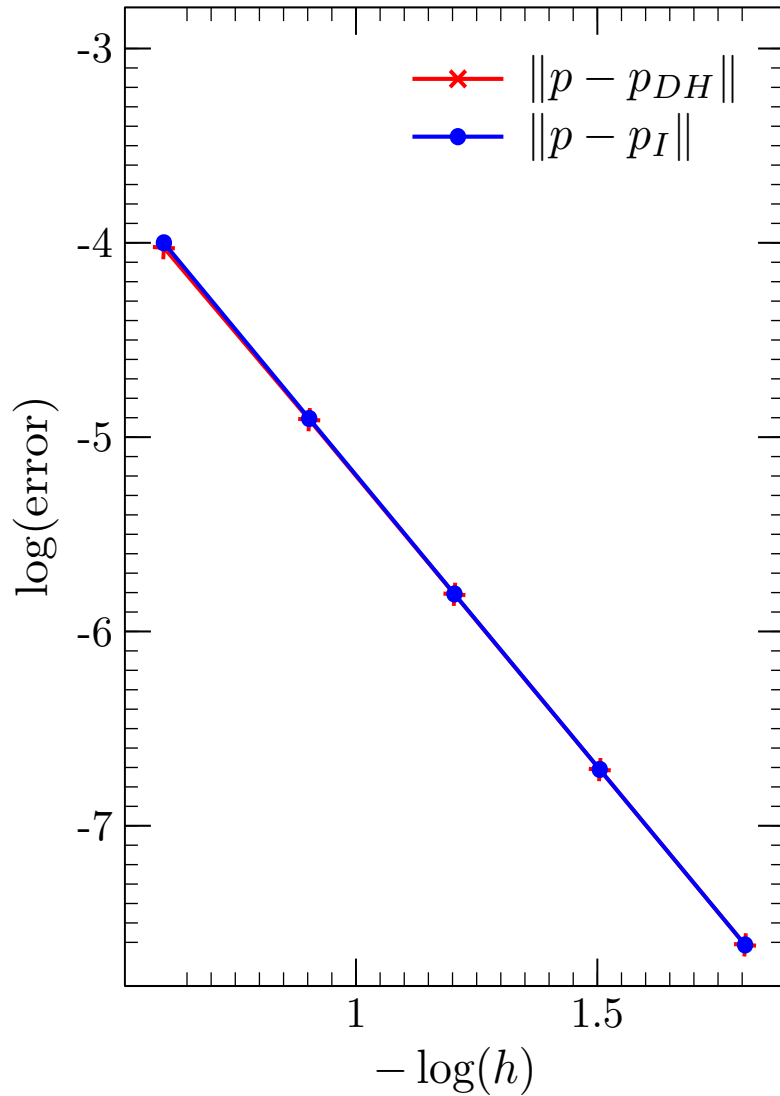
SDHM. h-convergence for $l = 1$



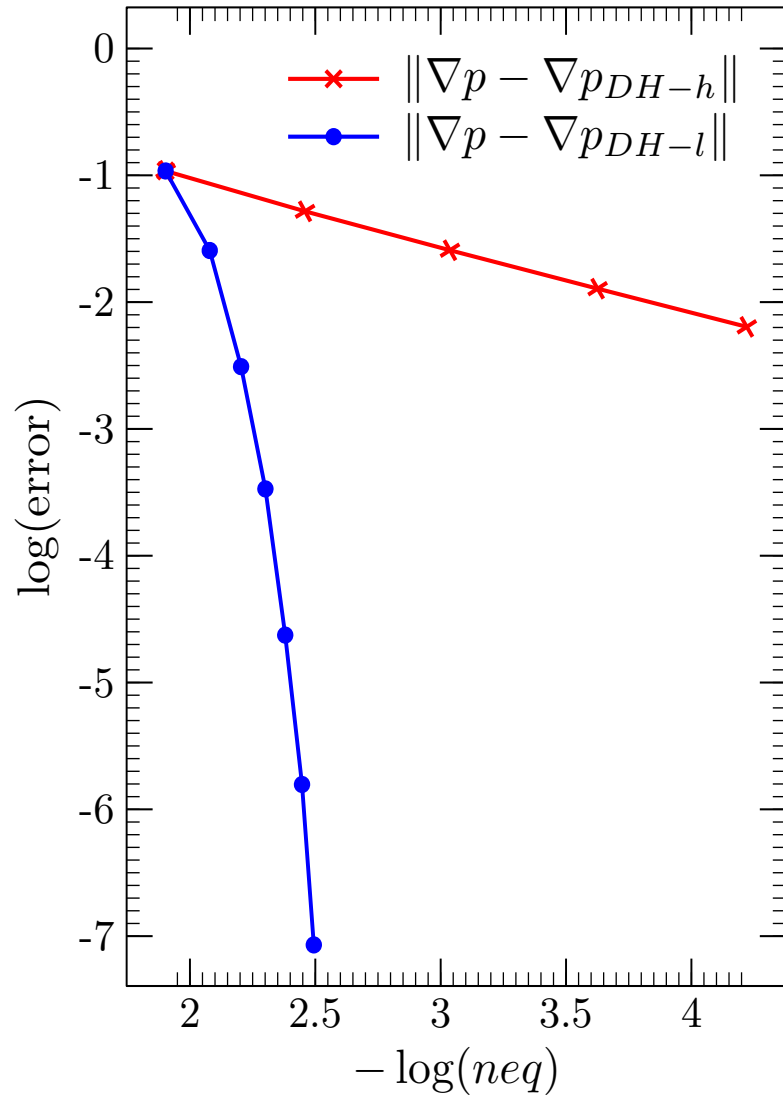
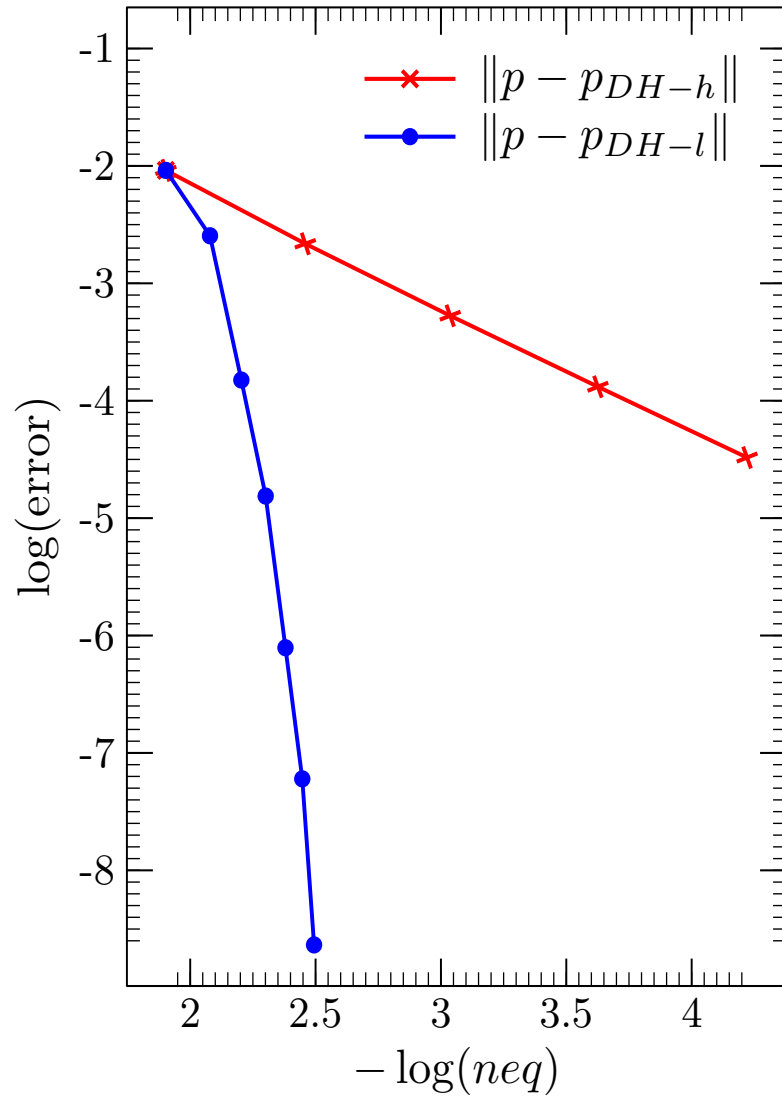
LDG-H ($l = 2$)



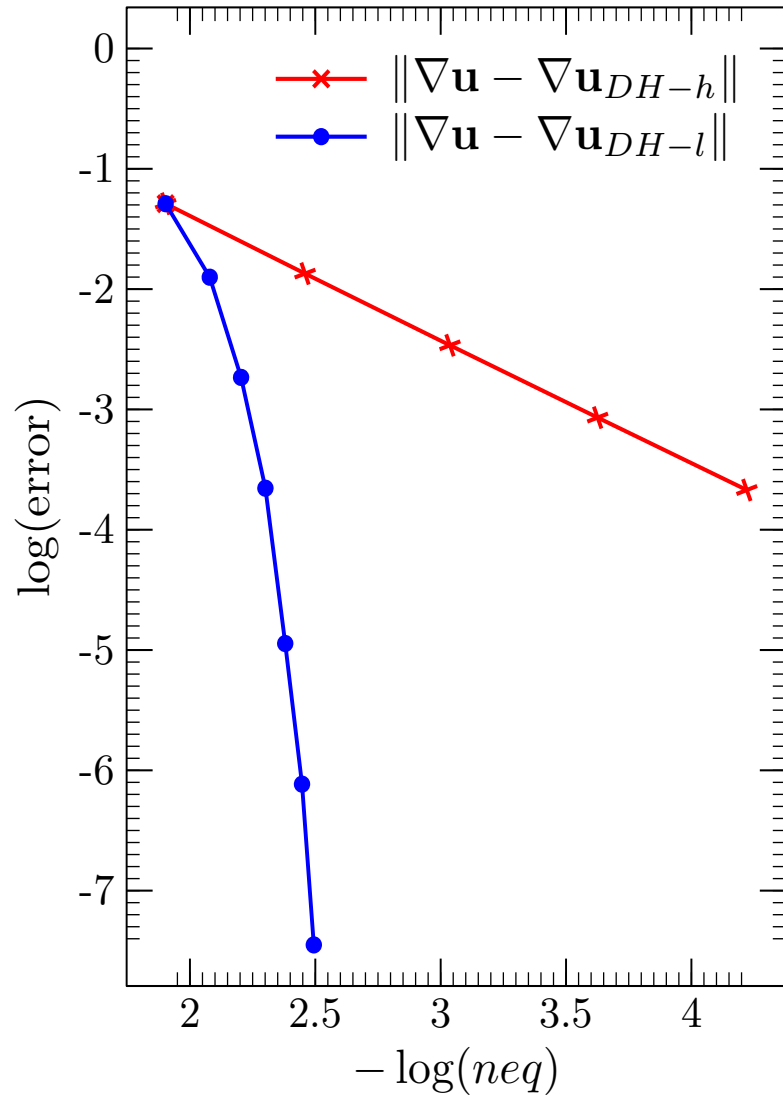
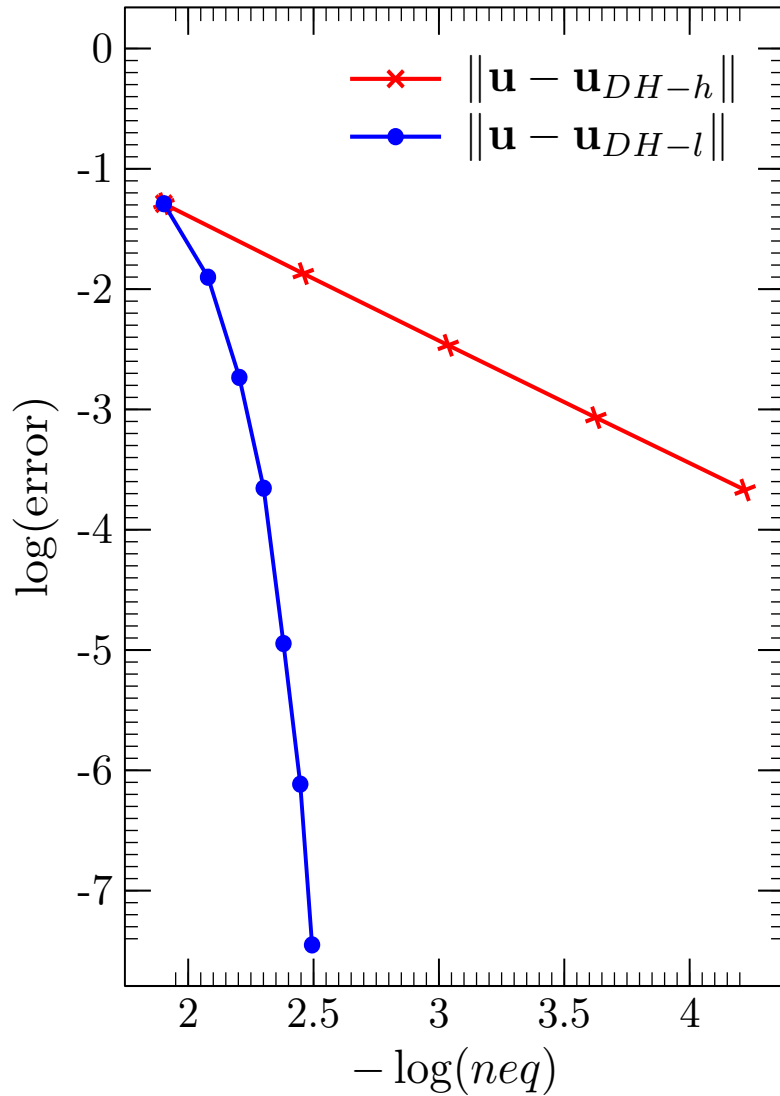
SDHM. h-convergence for $l = 2$



SDHM. $h \times l$ convergence



SDHM. $h \times l$ convergence



Heterogeneous Anisotropic Media

Domain: $\Omega = (-2, 2)^2$, Sub domain: $\Omega_I = (-1, 1)^2$

Hydraulic Conductivity:

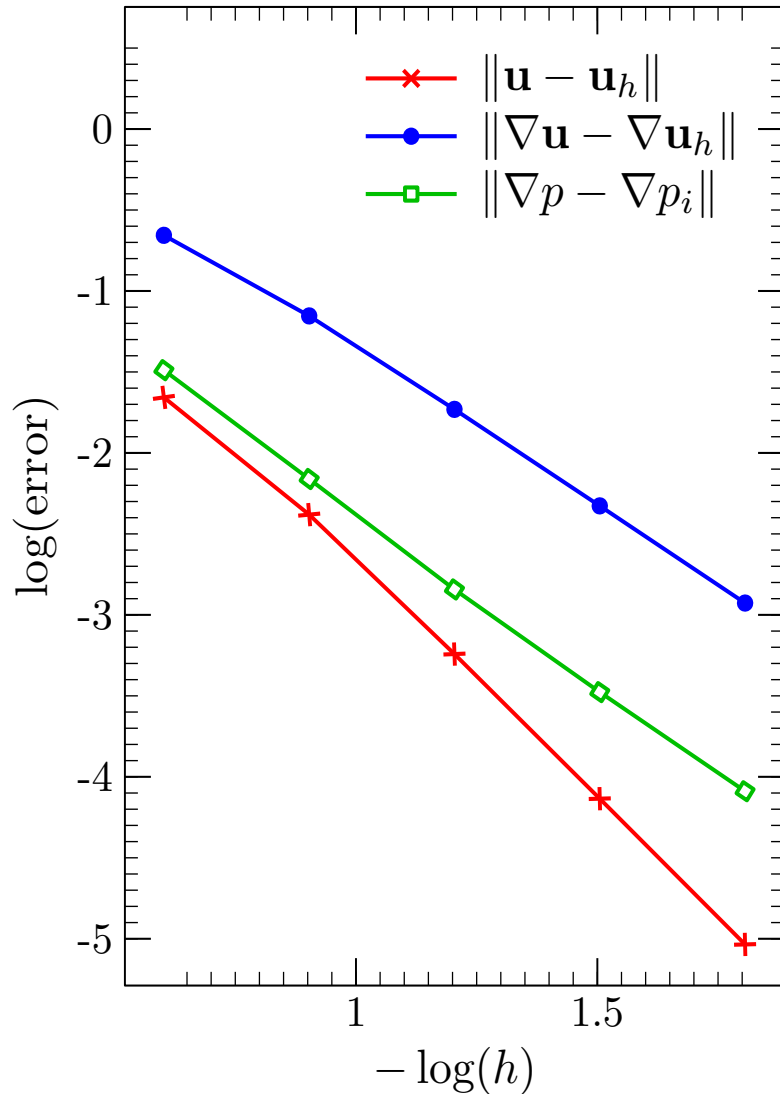
$$\mathbf{K} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad x \in \Omega_I \quad \mathbf{K} = \alpha \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \quad x \in \Omega/\Omega_I$$

Exact Solution:

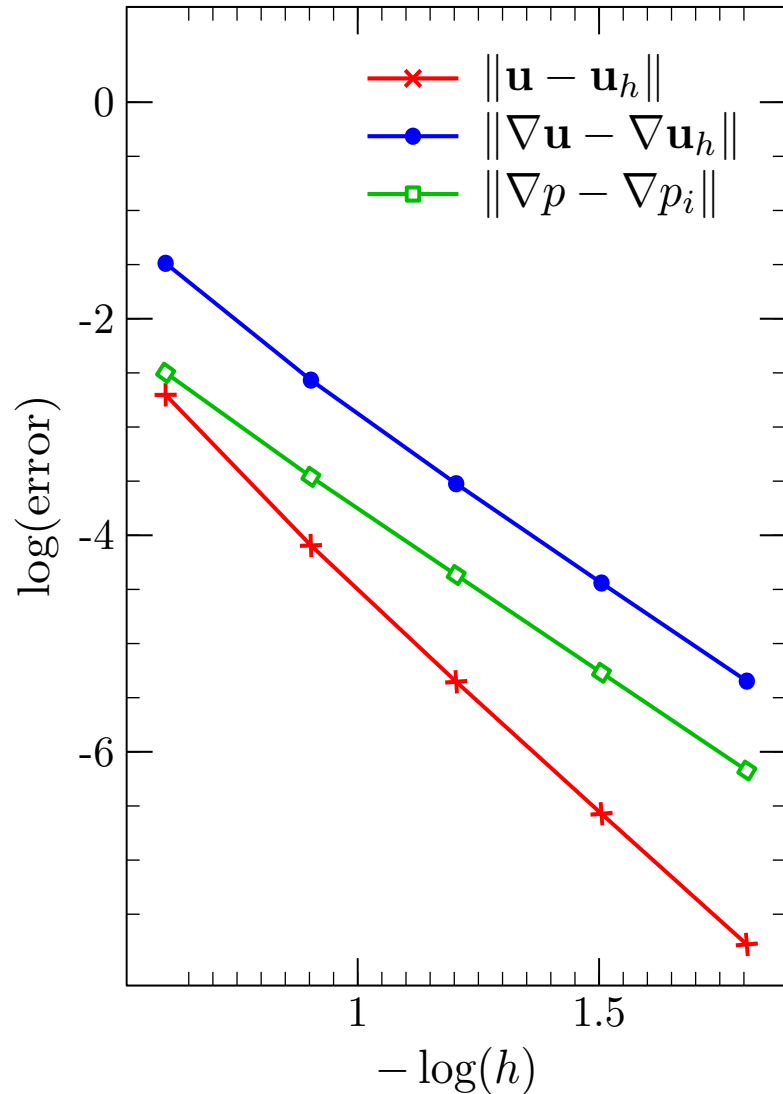
$$p = \begin{cases} \sin(\pi x) \sin(\pi y), & x \in \Omega_I \\ 2 \sin(\pi x) \sin(\pi y), & x \in \Omega/\Omega_I \end{cases}$$

SDHM: Heterogeneous medium

Q2Q2-3



Q3Q3-4



Concluding remarks

On Dual Hybrid Mixed Methods

- Adaptivity/Flexibility
 - h-refinement
 - Polynomial refinement
 - Irregular meshes
- Local conservation

On Stabilized Dual Hybrid Methods

- Additional flexibility
 - DHM (Dual Hybrid Mixed)
 - LDG-H (Local DG Hybridizable)
- Unconditional stability

Obrigado



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